



Proof of (3) $t(R)=R \cup R^2 \cup R^3 \cup ...$

• Consider arbitrary pairs <**x**,**y**> and <**y**,**z**>

 $\langle x,y \rangle \in R \cup R^2 \cup R^3 \cup \dots \land \langle y,z \rangle \in R \cup R^2 \cup R^3 \cup \dots$

 $\Rightarrow \langle x, z \rangle \in \mathbb{R} \cup \mathbb{R}^2 \cup \mathbb{R}^3 \cup \dots$

Therefore, by the transitivity of $R \cup R^2 \cup R^3 \cup ...$ We have $t(R) \subseteq R \cup R^2 \cup R^3 \cup ...$

• Next, we prove by induction that $\mathbb{R}^n \subseteq t(\mathbb{R})$.

For n=1, the statement is obviously true. Assume it holds for n=k.
For any <x,y>, we have

 $\langle x,y \rangle \in \mathbb{R}^{k+1} \Rightarrow \langle x,y \rangle \in \mathbb{R}^k \circ \mathbb{R} \Rightarrow \exists t \ (\langle x,t \rangle \in \mathbb{R}^k \land \langle t,y \rangle \in \mathbb{R})$

 $\Rightarrow \exists t (\langle x,t \rangle \in t(R) \land \langle t,y \rangle \in t(R)) \Rightarrow \langle x,y \rangle \in t(R) \quad (t(R) \text{ transitive})$

Thus, $R \cup R^2 \cup R^3 \cup ... \subseteq t(R)$





Let the relation matrices of R, r(R), s(R), t(R) be M, M_r, M_s and M_t, respectively. Then, we have:

> $M_r = M + E$ $M_s = M + M'$ $M_t = M + M^2 + M^3 + \dots$

where E is the identity matrix of the same order as M, and M' is the transpose of M.

Note: In the above equations, the matrix elements are added using logical addition.



4.3.2 Closure of Relations • Closure Operations on Relation Graphs

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- Let the relation graphs of R, r(R), s(R), t(R) be denoted by G, G_r, G_s, G_t, respectively.
 - Then, the vertex sets of G_r , G_s , G_t are the same as the vertex set of G_s .
- In addition to the edges of G, new edges are added in the following ways:
 - For each vertex in G, if there is no cycle, add a cycle. The resulting graph is G_r .
 - For each directed edge $x_i \rightarrow x_j$, (with $i \neq j$), add a reverse edge $x_i \rightarrow x_i$. The resulting graph is G_s .

• For each vertex x_i in G, examine all paths starting from x_i , if there is no edge from x_i to any node x_j in the path, add the corresponding edge. After checking all vertices, the resulting graph is G_t .



4.3.2 Closure of Relations **Closure Operations on Relation Graphs (e.g.)**



w>>>>Example: Let A={a,b,c,d}, R={<a,b>,<a,c>,<b,c>,<c,d>,<d,c>},

R and r(R), s(R), t(R) the relation graph is shown.





r(R)



s(R)

R



t(R)



4.3.2 Closure of Relations • Warshall's Algorithm for Transitive Closure



• Algorithm Idea: Consider a sequence of matrices M_0 , M_1 , ..., M_n of size n+1, where the element in the i-th row and j-th column of matrix M_k is denoted as $M_k[i,j]$. For k=0,1,...,n, $M_k[i,j]=1$ if and only if there exists a path from x_i to x_j in the relation graph of R, and this path passes through only the vertices in $\{x_1, x_2, ..., x_k\}$ except for the endpoints. It is easy to prove that M_0 is the relation matrix of R, and M_n corresponds to the transitive closure of R.

■ Warshall Algorithm: Starting from M_0 , calculate M_1 , M_2 , ..., until M_n . From $M_k[i, j]$ to compute $M_{k+1}[i, j]$: $i, j \in V$. The vertex set $V_1 = \{1, 2, ..., k\}$, $V_2 = \{k+2, ..., n\}$, $V = V_1 \cup \{k+1\} \cup V_2$, $M_{k+1}[i,j] = 1 \Leftrightarrow$ There exists a path i to j. that only passes through the points in $V_1 \cup \{k+1\}$.

4.3.2 Closure of Relations Warshall's Algorithm for Transitive Closure (cont.)

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These paths are divided into two categories:

- •Category 1: Paths that only pass through the points in V_1
- •Category 2: Paths that pass through point k+1

For Category 1 paths: $M_k[i,j]=1$

For Category 2 paths:

 $M_{k}[i,k+1]=1 \land M_{k}[k+1,j]=1$







- Algorithm 4.1: Warshall Algorithm
- Input: M (relation matrix of R)
- Output: M_t (relation matrix of t(R))
- 1. $M_t \leftarrow M$
- 2. for $k \leftarrow 1$ to n do
- 3. for $i \leftarrow 1$ to n do
- 4. for $j \leftarrow 1$ to n do
- 5. $M_t[i, j] \leftarrow M_t[i, j]$ or $M_t[i, k] \cdot M_t[k, j]$

```
Time Complexity: T(n)=O(n^3)
```







Objective :

Key Concepts :





Discrete Mathematics 2025 Spring



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- 4.1 Definition and Representation of Relations
- 4.2 Operations on Relations
- 4.3 Properties of Relations
- 4.4 Equivalence Relations and Partial Order Relations





4.4.1 Equivalence Relations

- 4.4.2 Equivalence Classes and Quotient Sets
- 4.4.3 Partition of a Set
- 4.4.4 Partial Order Relations
- 4.4.5 Partially Ordered Sets and Hasse Diagrams



L Equivalence relation \sim



Definition 4.18: let *R* be a relation on a non-empty set. If *R* is reflexive, symmetric, and transitive, then *R* is called an *equivalence relation* on *A*. If *R* is an equivalence relation and $\langle x,y \rangle \in R$, we say that *x* is equivalent to *y*, denoted as $x \sim y$.

Example: Verify that *R* is an equivalence relation on *A*.

Let $A=\{1, 2, ..., 8\}$, and define the relation R on A as follows : $R=\{\langle x,y \rangle \mid x,y \in A \land x \equiv y \pmod{3}\}$

where $x \equiv y \pmod{3}$ means that x and y are congruent modulo 3, i.e., the remainder when x is divided by 3 is equal to the remainder when y is divided by 3.



L Equivalence relation \sim (e.g.)



**>>>Example: Let $A=\{1, 2, ..., 8\}$, and define the relation R on A as follows : $R=\{<x,y> | x,y \in A \land x \equiv y \pmod{3}\}$ where $x \equiv y \pmod{3}$ means that x and y are congruent modulo 3, i.e., the remainder when x is divided by 3 is equal to the remainder when y is divided by 3.

It is easy to verify that *R* is an equivalence relation on *A*, because: $\forall x \in A$, if $x \equiv x \pmod{3}$ (reflexivity) $\forall x, y \in A$, if $x \equiv y \pmod{3}$, then $y \equiv x \pmod{3}$ (symmetry) $\forall x, y, z \in A$, if $x \equiv y \pmod{3}$, $y \equiv z \pmod{3}$, then $x \equiv z \pmod{3}$ (transitivity)





& Equivalence relation graph (e.g.)



Relation Graph of the Modulo 3 Equivalence Relation on A

The relation graph of **R** is shown below :







4.4.1 Equivalence Relations

- 4.4.2 Equivalence Classes and Quotient Sets
- 4.4.3 Partition of a Set
- 4.4.4 Partial Order Relations
- 4.4.5 Partially Ordered Sets and Hasse Diagrams





Definition 4.19: let *R* be an equivalence relation on a non-empty set *A*, ∀*x*∈*A*, define [*x*]_{*R*} = { *y* | *y*∈*A* ∧ *xRy* } We call [*x*]_{*R*} the *equivalence class* of *x under R*, or simply the equivalence class of *x*, denoted as [*x*].

Note: $[x]_R$ is the set of all elements in A that are equivalent to x under the relation R.

 $[x]_R = \{y \in A \mid (x,y) \in R\}$





www.second content of the module 3 equivalence
relation on A={1, 2, ..., 8}:
 [1]=[4]=[7]={1,4,7}
 [2]=[5]=[8]={2,5,8}
 [3]=[6]={3,6}

• The three equivalence classes with remainders 1, 2, and 0 are disjoint, and their union is **A**.





- **Theorem 4.8:** Partition Theorem of Equivalence Classes.
 - Let **R** be an equivalence relation on a non-empty set **A**

The following conclusions hold:

(1) $\forall x \in A$, [x] is a non-empty subset of A.

(2) ∀*x*, *y*∈*A*, if *xRy*, then [*x*]=[*y*].

(3) $\forall x, y \in A$, if $x \not\in X$ y, then [x] and [y] are disjoint.

(4) $\bigcup_{x \in A} [x] = A$, the union of all equivalence classes is equal to A.





Theorem 4.8(1): $\forall x \in A$, [x] is a non-empty subset of A.

Proof: From the definition of equivalence classes, $\forall x \in A$, we have $[x] \subseteq A$. By reflexivity, xRx, so $x \in [x]$, which implies that [x] is non-empty. Since all elements in the equivalence class [x] are selected from the set A, it follows that [x] is a subset of A.

■ Theorem 4.8(2): ∀x, y∈A, if xRy, then [x]=[y].

Proof: For any element a in [x], $(x,a) \in R$. Since $(x,y) \in R$ and R is transitive, we can conclude that $(y,a) \in R$, so $a \in [y]$. This proves that $[x] \subseteq [y]$.

Similarly, we can prove that $[y] \subseteq [x]$. Therefore [x]=[y].







Theorem 4.8(3): ∀x, y∈A, if x y, then [x] and [y] are disjoint.
Proof:

Suppose $[x] \cap [y] \neq \emptyset$, then there exists an element $z \in [x] \cap [y]$, which implies $z \in [x] \land z \in [y]$, then $\langle x, z \rangle \in R \land \langle y, z \rangle \in R$ holds.

By the transitivity and symmetry of *R*, then <x,y>∈*R*, contradicted to x *R*y.









4.4.2 Equivalence Classes and Quotient Sets Quotient Sets



Definition 4.20: Let *R* be an equivalence relation on a nonempty set *A*. The set of equivalence classes of *R* is called the *quotient set* of *A* with respect to *R*, denoted by *A*/*R*,

 $A/R = \{ [x]_R \mid x \in A \}$

Example: Let A={1, 2, ..., 8}, the quotient set of A with respect to the equivalence relation R modulo 3 is: A/R = { {1, 4,7}, {2, 5, 8}, {3, 6} }

The quotient sets of A with respect to the identity relation and the universal relation are:

 $A/I_A = \{ \{1\}, \{2\}, \dots, \{8\} \}$ $A/E_A = \{ \{1, 2, \dots, 8\} \}$





- **4.4.1 Equivalence Relations**
- 4.4.2 Equivalence Classes and Quotient Sets
- 4.4.3 Partition of a Set
- 4.4.4 Partial Order Relations
- 4.4.5 Partially Ordered Sets and Hasse Diagrams



4.4.3 Partition of a Set **Quotient Sets**

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Definition 4.21: Let A be a non-empty set, A family of subset π (π⊆P(A)), if it satisfies the following conditions:
(1) Ø∉π; (2) ∀x∀y (x,y∈π∧x≠y→x∩y=Ø); (3) ∪π=A Then π is called a *partition of A*, and the element of π are called blocks of the partition of A.

Example: Let *A*={*a*, *b*, *c*, *d*}, given the partitions:

 $\pi_{1} = \{\{a, b, c\}, \{d\}\}, \qquad \pi_{2} = \{\{a, b\}, \{c\}, \{d\}\}\}$ $\pi_{3} = \{\{a\}, \{a, b, c, d\}\}, \qquad \pi_{4} = \{\{a, b\}, \{c\}\}\}$ $\pi_{5} = \{\emptyset, \{a, b\}, \{c, d\}\}, \qquad \pi_{6} = \{\{a, \{a\}\}, \{b, c, d\}\}\}$ Then π_{1}, π_{2} are partitions of A, while the others are not.



- The quotient set A/R is a partition of A.
- Different quotient sets correspond to different partitions.
- Given any partition π of A, we define a relation **R** on A as follows: $R = \{\langle x, y \rangle \mid x, y \in A \text{ and } [x]_{\pi} = [y]_{\pi} \}$

 $([x]_{\pi}=[y]_{\pi}: x \text{ and } y \text{ are in the same partition block of } \pi)$

Then, R is an equivalence relation on A, and the quotient set determined by this equivalence relation is exactly π .

Example: List all equivalence relations on *A*={1,2,3}

Solution approach:

First, determine all partitions of *A*, and then write out the corresponding equivalence relations based on these partitions.



4.4.3 Partition of a Set Set Partitions and Equivalence Relation(e.g.)



Determine all partitions of $A = \{1, 2, 3\}$



 π_1 corresponds to the universal relation E_A

 π_5 corresponds to the identity relation I_A

 $π_2, π_3 π_3$ correspond to the equivalence relations $R_2, R_3 π R_4$.

 $R_{2} = \{ <2, 3 >, <3, 2 > \} \cup I_{A}$ $R_{3} = \{ <1, 3 >, <3, 1 > \} \cup I_{A}$ $R_{4} = \{ <1, 2 >, <2, 1 > \} \cup I_{A}$





seample: Let A={1,2,3,4}

Define a binary relation **R** on **A**×**A**:

 $\langle x, y \rangle, \langle u, v \rangle \in R \Leftrightarrow x + y = u + v$, find the partition induced by R.

Solution: A×A={<1,1>, <1,2>, <1,3>, <1,4>, <2,1>, <2,2>, <2,3>,

<2,4>,<3,1>, <3,2>, <3,3>, <3,4>, <4,1>, <4,2>,<4,3>, <4,4>}

According to the sum condition <x,y> and x+y=2,3,4,5,6,7,8 which partition A×A into 7 equivalence classes:

 $(A \times A)/R = \{\{<1,1>\}, \{<1,2>,<2,1>\}, \{<1,3>, <2,2>, <3,1>\},$ $\{<1,4>, <2,3>, <3,2>, <4,1>\}, \{<2,4>, <3,3>, <4,2>\},$ $\{<3,4>, <4,3>\}, \{<4,4>\}\}$





- **4.4.1 Equivalence Relations**
- 4.4.2 Equivalence Classes and Quotient Sets
- 4.4.3 Partition of a Set
- 4.4.4 Partial Order Relations
- 4.4.5 Partially Ordered Sets and Hasse Diagrams





Definition 4.22:

A relation on a non-empty set that is **reflexive**, **antisymmetric**, **and transitive** is called a *partial order relation* on *A*, denoted *by* \leq . If $\langle x, y \rangle \in \leq$, then we write it as $x \leq y$, which is read as x "less than or equal" y.

- The **identity relation** I_A on set A is a partial order relation on A.
- The less than or equal to relation, divisibility relation, and subset inclusion relation are also partial order relations on their respective sets.



- 4.4.4 Partial Order Relations
 Characteristics of Partial Order Comparability and Total Order
 Definition 4.23: Comparability
 Let *R* be a partial order relation on a non-empty set *A*,
 For *x*, *y*∈*A*, we say that *x* and *y* are comparable if and only if *x*≤*y* or *y*≤*x*.
 - Condition for incomparability: If no partial order relation relates **x** and **y**, then they are **not comparable**.
 - Definition 4.24: Total Order
 - If **R** is a partial order on a non-empty set A, $\forall x, y \in A$, x and y are always comparable, **R** is called a *total order*.





Examples:

- The "less than or equal to" relation on numerical sets (such as real numbers and integers) is a total order.'
- The **divisibility relation** is **not a total order** on the set of positive integers.
- Definition 4.25: Covering

 $x,y \in A$, if $x \prec y$ and there is no $z \in A$ such that $x \prec z \prec y$, then we say that y covers x.

• Such as: On the set {1, 2, 4, 6} with the divisibility relation:

2 covers1, 4 and 6 covers2.

4 doesn't cover 1.





- **4.4.1 Equivalence Relations**
- 4.4.2 Equivalence Classes and Quotient Sets
- 4.4.3 Partition of a Set
- 4.4.4 Partial Order Relations
- 4.4.5 Partially Ordered Sets and Hasse Diagrams



4.4.5 Partially Ordered Sets and Hasse Diagrams



- Definition 4.26: Partially ordered set.
 - A *partially ordered set* (poset) consists of a set A together with a partial order relation \leq , denoted as $<A, \leq >$.
- Such as:
 - The set of integers with the "less than or equal to" relation forms a poset <**Z**,≤>.
 - The power set P(A) with the subset inclusion relation forms a poset $\langle P(A), R_{\subseteq} \rangle$.



4.4.5 Partially Ordered Sets and Hasse Diagrams Simplified representation of a poset - Hasse diagram



Hesse Diagram: A simplified graphical representation of a partial order that eliminates reflexivity, antisymmetry, and transitivity in the diagram.

Characteristics:

- •Each node has no self-loops.
- •The order between two connected nodes is represented by their relative position: Lower-positioned elements come earlier in the order.
- •There is an edge between two nodes **if and only if** they have a covering relation.
- A Hasse diagram is a special type of relational graph for posets, with transitive edges removed and implicit direction.





Example : Given the Hasse diagram of the **partially ordered set** <*A*,*R* > shown below, find the expression for the **set** *A* **and the relation** *R*.

Solution: ①Identify the Elements in A;②Extract the Covering Relations;③Complete transitive and reflexive relations.



 $A=\{a, b, c, d, e, f\}$ $R=\{<b,d>,<b,e>,<b,f>,<c,d>,<c,e>,<c,f>,<d,f>,<e,f>\}\cup I_A$





- Definition 4.27: Let<A,≼>be a partially ordered set (poset) , B_A, y∈B.
- (1) if $\forall x (x \in B \rightarrow y \leq x)$, then y is called the *least element* of *B*.
- (2) if $\forall x (x \in B \rightarrow x \leq y)$, then y is called the *greatest element* of *B*.
- (3) If $\forall x (x \in B \land x \preccurlyeq y \rightarrow x = y)$, then y is called a *minimal element* of *B*.
- (4) If $\forall x (x \in B \land y \preccurlyeq x \rightarrow x = y)$, y is called a *maximal element of B*.
- Properties:
 - In a finite set, minimal and maximal elements always exist and may not be unique.
 - Least and greatest elements are not guaranteed to exist, but if they do, they are unique.
 - The least element is always a minimal element.
 - The greatest element is always a maximal element.
 - Isolated nodes are both minimal and maximal elements. CAMEA []

4.4.5 Partially Ordered Sets and Hasse Diagrams
Upper/lower bounds, supremum, infimum of a poset



- Definition 4.28: Let<A, \leq > be a partially ordered set (poset), and let $B \subseteq A$, $y \in A$.
 - (1) If $\forall x \ (x \in B \rightarrow x \leq y)$, then y is called an **upper bound** of B.
 - (2) If $\forall x \ (x \in B \rightarrow y \leq x)$, then y is called a lower bound of B.
 - (3) Let C={y | y is an upper bound of B}, the least element of C, if it exists, is called the least upper bound (supremum) of B or the supremum.
 - (4) Let D={y | y is a lower bound of B}, The greatest element of D, if it exists, is called the greatest lower bound (infimum) of B or the infimum.



Properties:

- Lower bounds, upper bounds, infimum, and supremum are **not always** guaranteed to exist.
- Lower bounds and upper bounds, if they exist, may not be unique.
- The infimum and supremum, if they exist, are unique.
- The least element of a set is its infimum, and the greatest element is its supremum, however, the **reverse is not always true**.



(1) Given the partially ordered set $\langle A, \preccurlyeq \rangle$ as shown in the diagram, find the minimal elements, least element, maximal elements, and greatest element of A.

(2) Let $B = \{ b, c, d \}$, find the lower bounds, upper bounds, infimum (greatest lower bound), and supremum (least upper bound) of B.

```
Solution (1) : Minimal elements: a, b, c;
Maximal elements: a, f;
No least element or greatest element.
Solution (2) :
Lower bounds and greatest lower bound do not exist.
Upper bounds: d, f
Least upper bound (supremum): d
```



 \mathbf{O}_a





Special Subsets of a Poset: Chains and Antichains



- Definition 4.29: Let <A, <> be a partially ordered set (poset), and B_A.
- (1) If for all $\forall x, y \in B$, x and y are comparable, then B is called a *chain* in A, The number of elements in B is called the length of the chain.
- (2) If for all ∀x,y∈B, x≠y, x and y are not comparable, then B is called an antichain in A, The number of elements in B is called the length of the antichain..
- Examples: In the poset <{1,2,...,9}, |>中, {1,2,4,8} is a chain of length 4, {1,4} is a chain of length 2, {2,3} is an antichain of length 2. The singleton set {2 has length 1 and is both a chain and an antichain.



- 4.4.5 Partially Ordered Sets and Hasse Diagrams
 - Antichain Decomposition Algorithm for Poset



- Theorem 4.9: Let <A, ≤> be a partially ordered set (poset). If the length of the longest chain in A is n, then the poset can be decomposed into n disjoint antichains.
- Algorithm 4.2: Antichain Decomposition Algorithm for Posets.

Input: A partially ordered set A

Output: Antichains B_1 , B_2 , ...

- 1. *i*←1
- **2.** $B_i \leftarrow$ the set of all **maximal elements** in A (which is an antichain)
- 3. $A \leftarrow A B_i$
- **4.** if *A*≠Ø
- 5. *i*←*i*+1
- 6. Go to 2



- 4.4.5 Partially Ordered Sets and Hasse Diagrams
- **U** Topological Sorting Extending a Poset to a Total Order



- Topological Sorting: Expanding a partially ordered set (poset) into a totally ordered set is called topological sorting.
- Algorithm 4.3: Topological Sorting

Input: A partially ordered set A

Output: A sorted order of elements in A

- 1. *i*←1
- 2. Select a minimal element a_i from A and consider it the smallest element
- 3. $A \leftarrow A \{a_i\}$
- 4. if *A*≠Ø
- 5. *i*←*i*+1
- 6. Go to 2



4.4.5 Partially Ordered Sets and Hasse Diagrams Jopological Sorting - Extending a Poset to a Total Order(e.g.)



Examle: A set of tasks *A* is given with partial order constraints, and its Hasse diagram is shown in the figure.

$$A = \{T_1, T_2, T_3, T_4, T_5, S_1, T_6, S_2, T, T_9, T_{10}\}$$

Check whether the following topological order is valid.

such as:

$$T_1, T_2, T_3, T_4, S_1, T_5, T_6, S_2, T, T_9, T_{10};$$

 $T_1, T_2, T_3, T_4, S_1, T_6, S_2, T, T_9, T_5, T_{10};$





Objective :

Key Concepts :

